

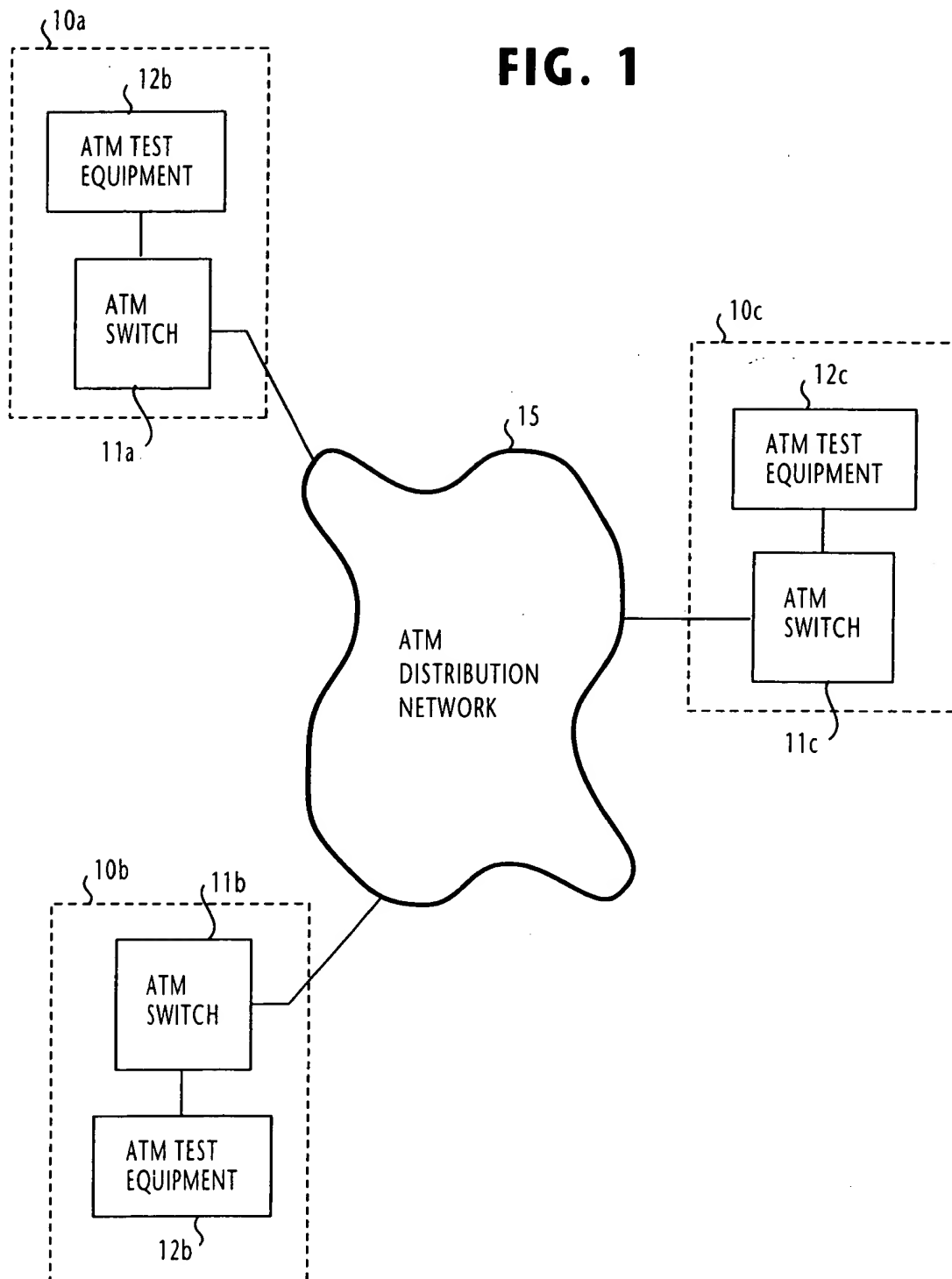
FIG. 1

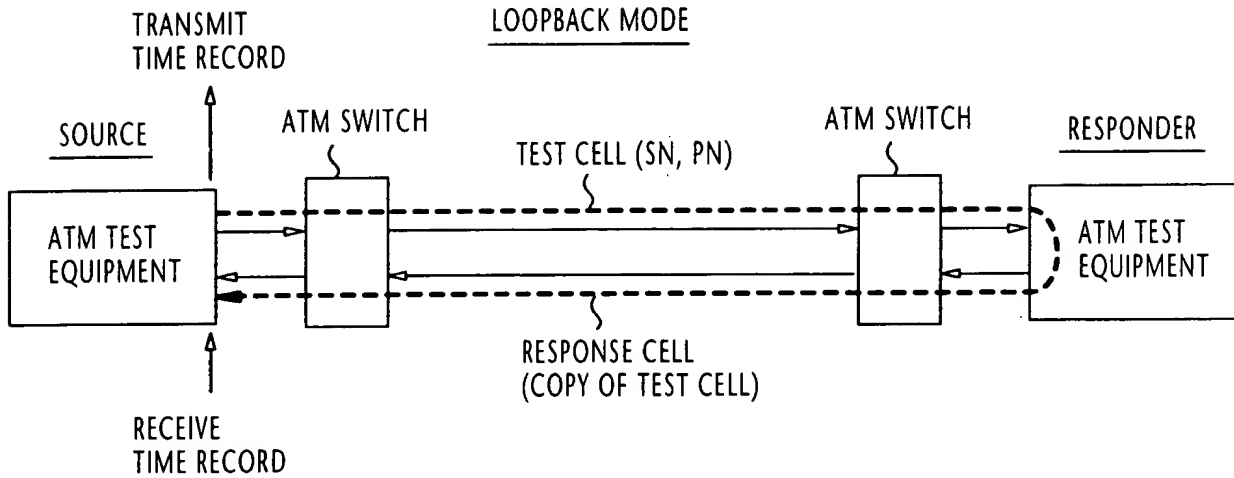
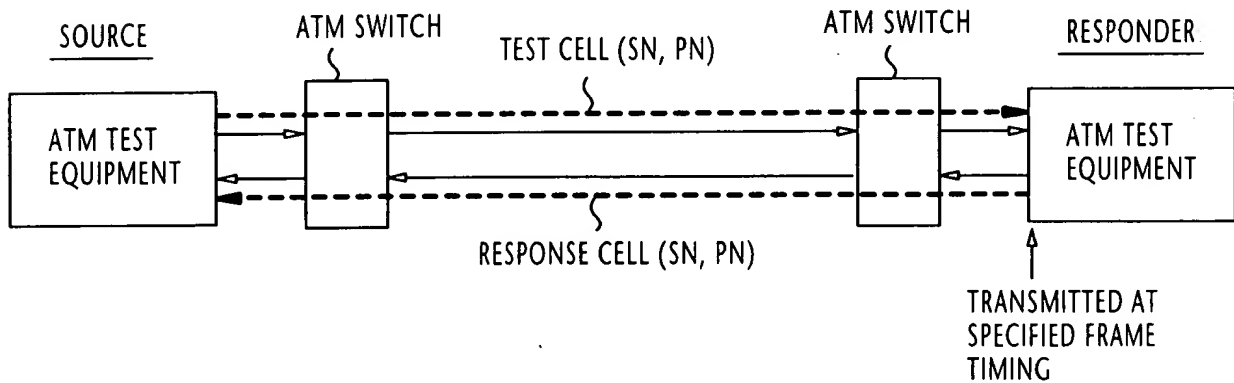
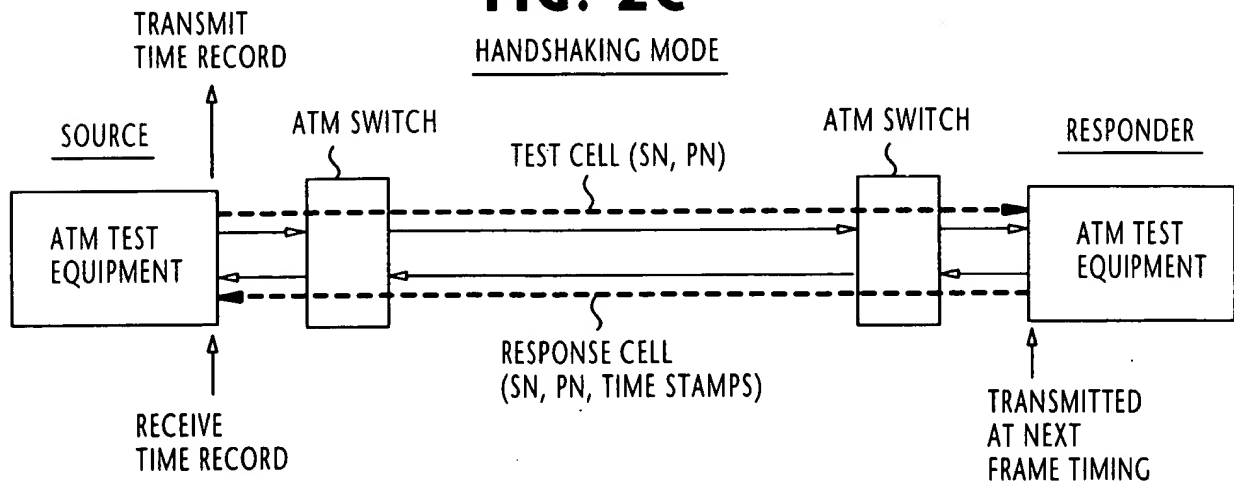
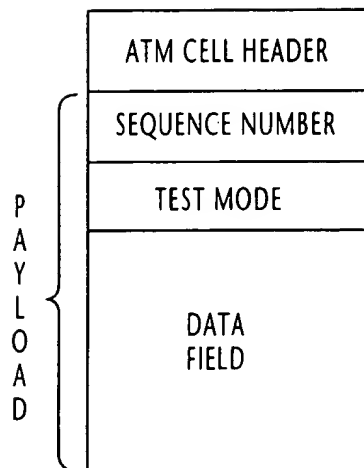
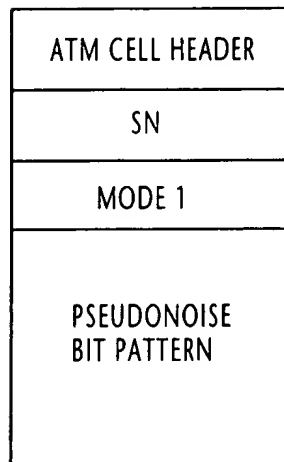
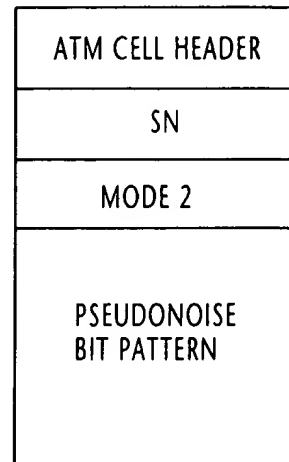
FIG. 2ALOOPBACK MODE**FIG. 2B**TWO-WAY MODE**FIG. 2C**HANDSHAKING MODE

FIG. 3A**FIG. 3B**

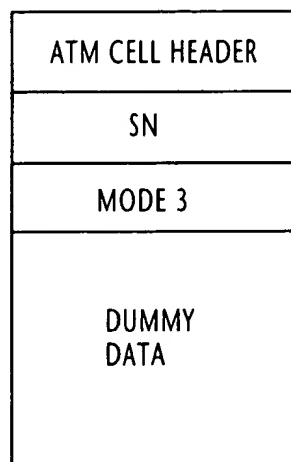
SOURCE AND RESPONDER
NODES (LOOPBACK MODE)

**FIG. 3C**

SOURCE AND RESPONDER
NODES (TWO-WAY MODE)

**FIG. 3D**

SOURCE NODE
(HANDSHAKING MODE)

**FIG. 3E**

RESPONDER NODE
(HANDSHAKING MODE)

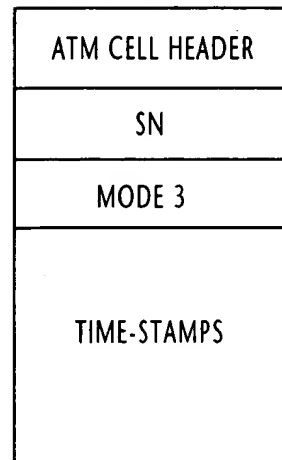


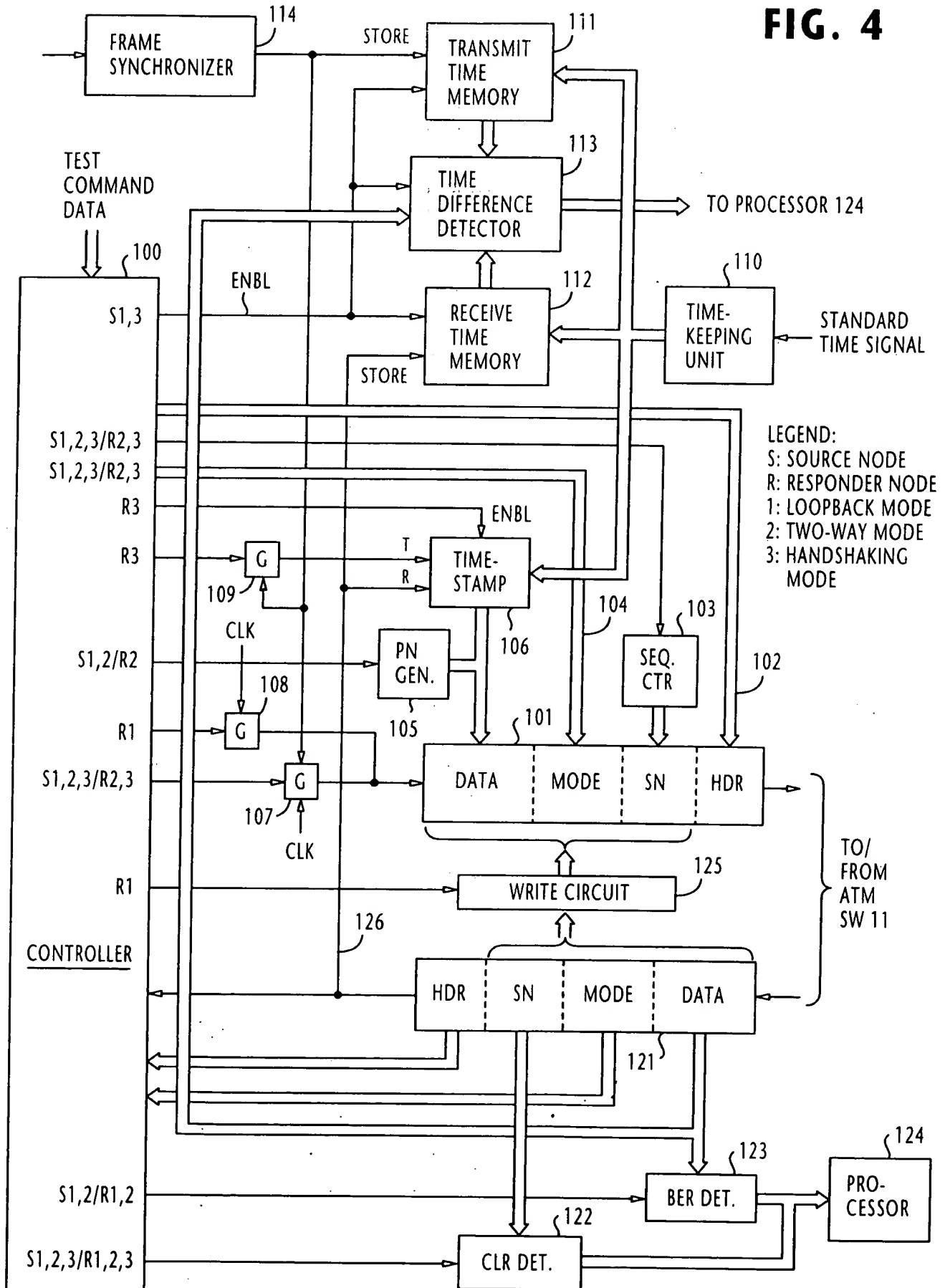
FIG. 4

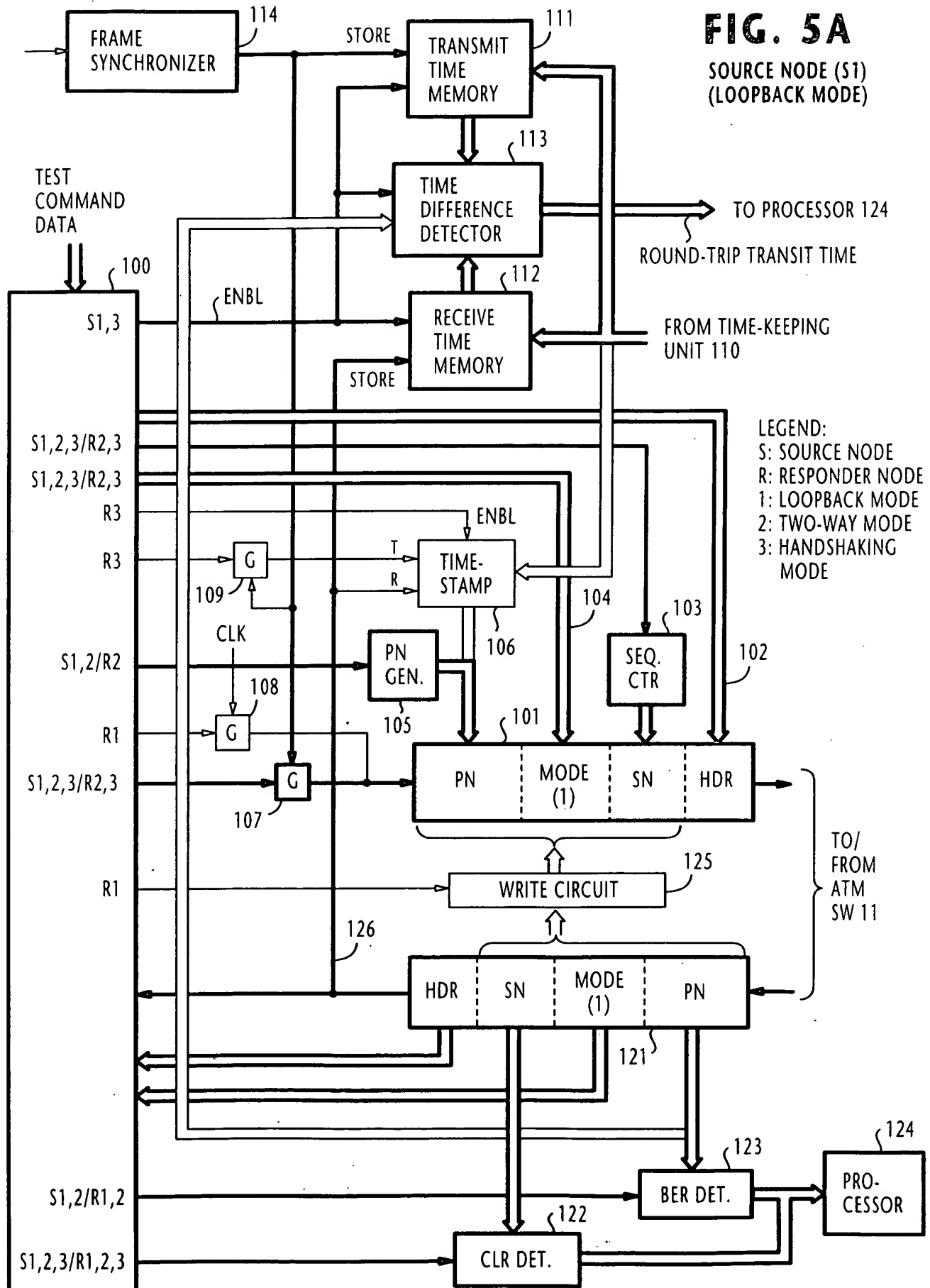
FIG. 5ASOURCE NODE (S1)
(LOOPBACK MODE)

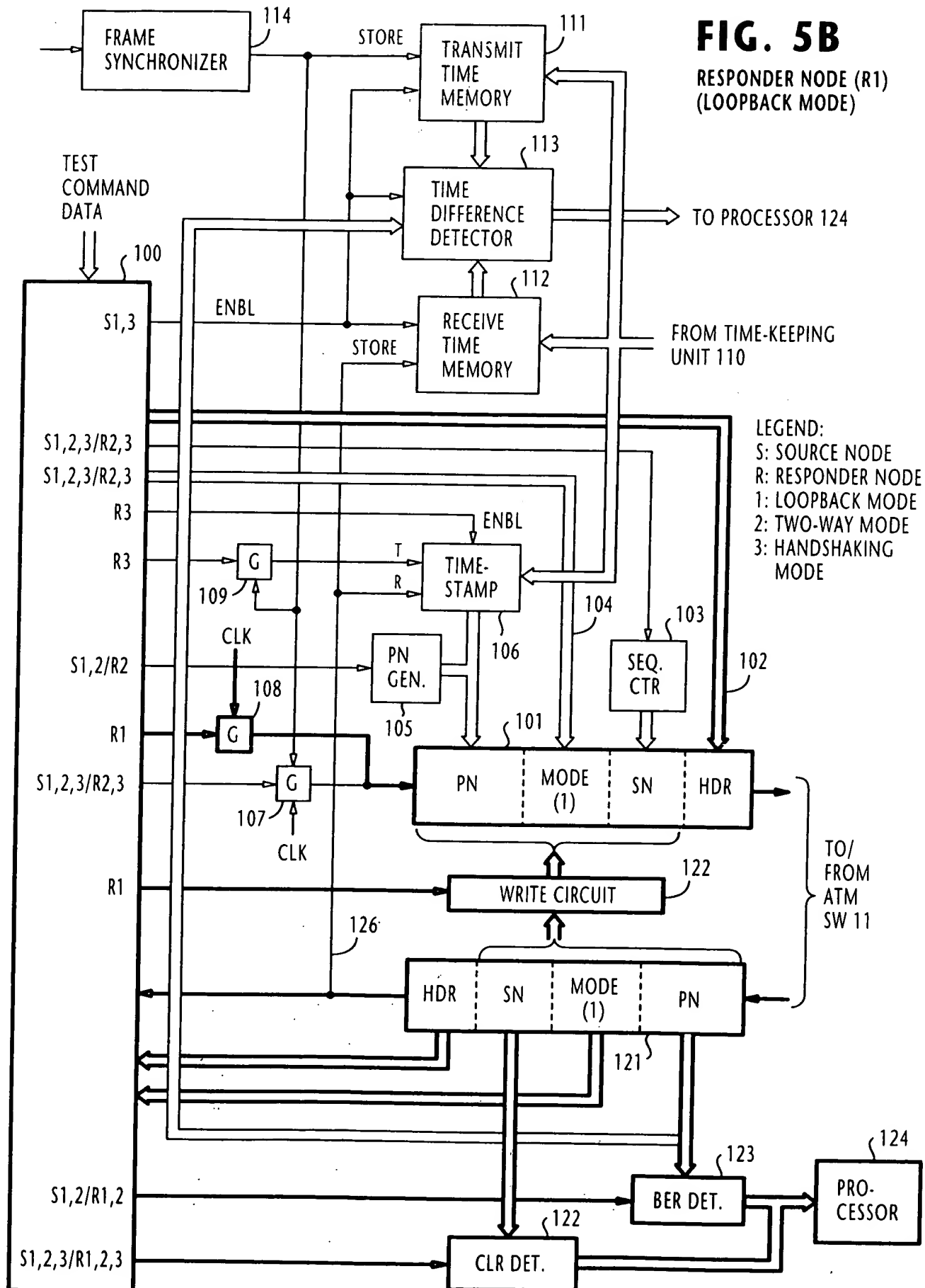
FIG. 5B**RESPONDER NODE (R1)
(LOOPBACK MODE)**

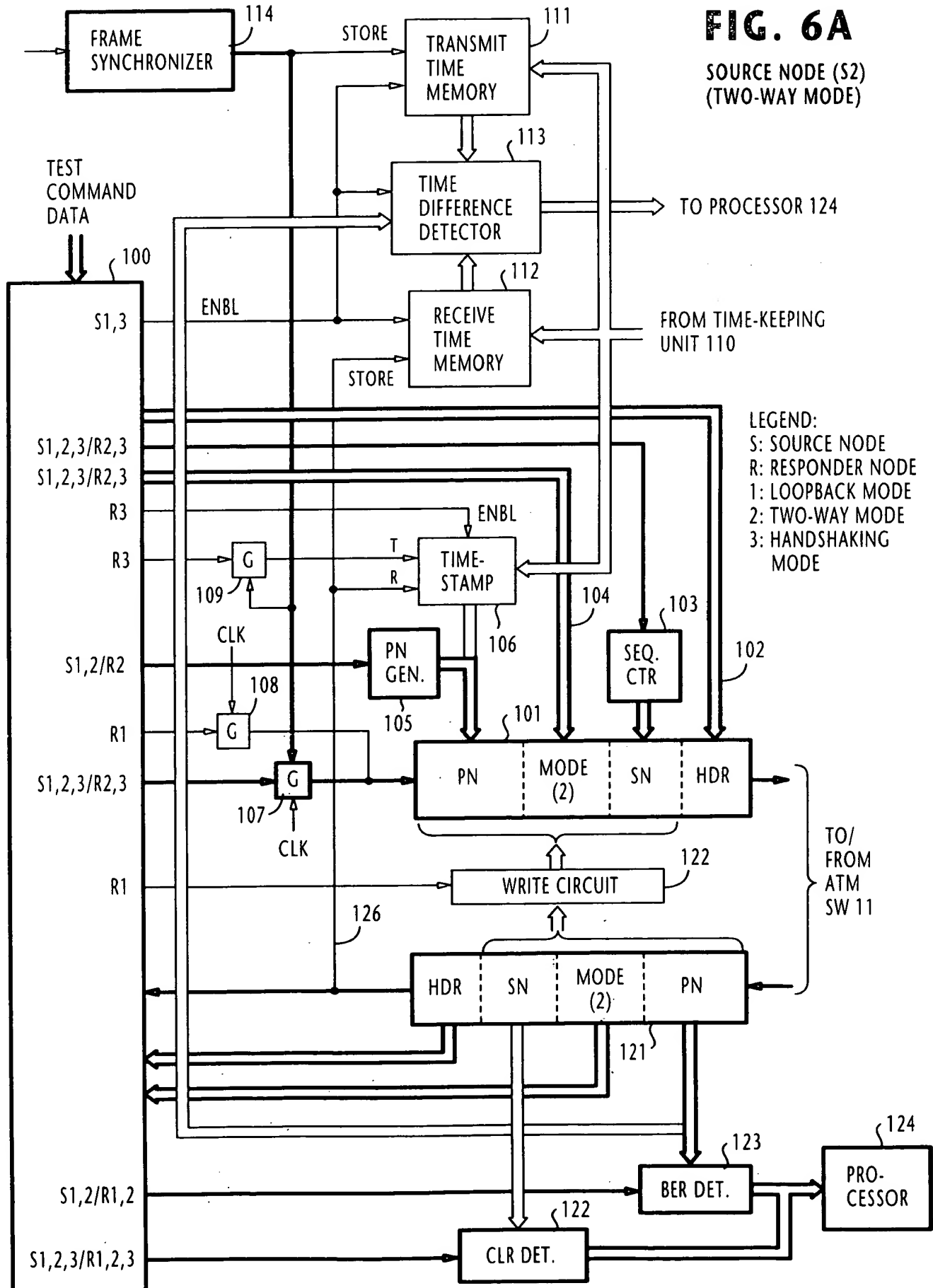
FIG. 6ASOURCE NODE (S2)
(TWO-WAY MODE)

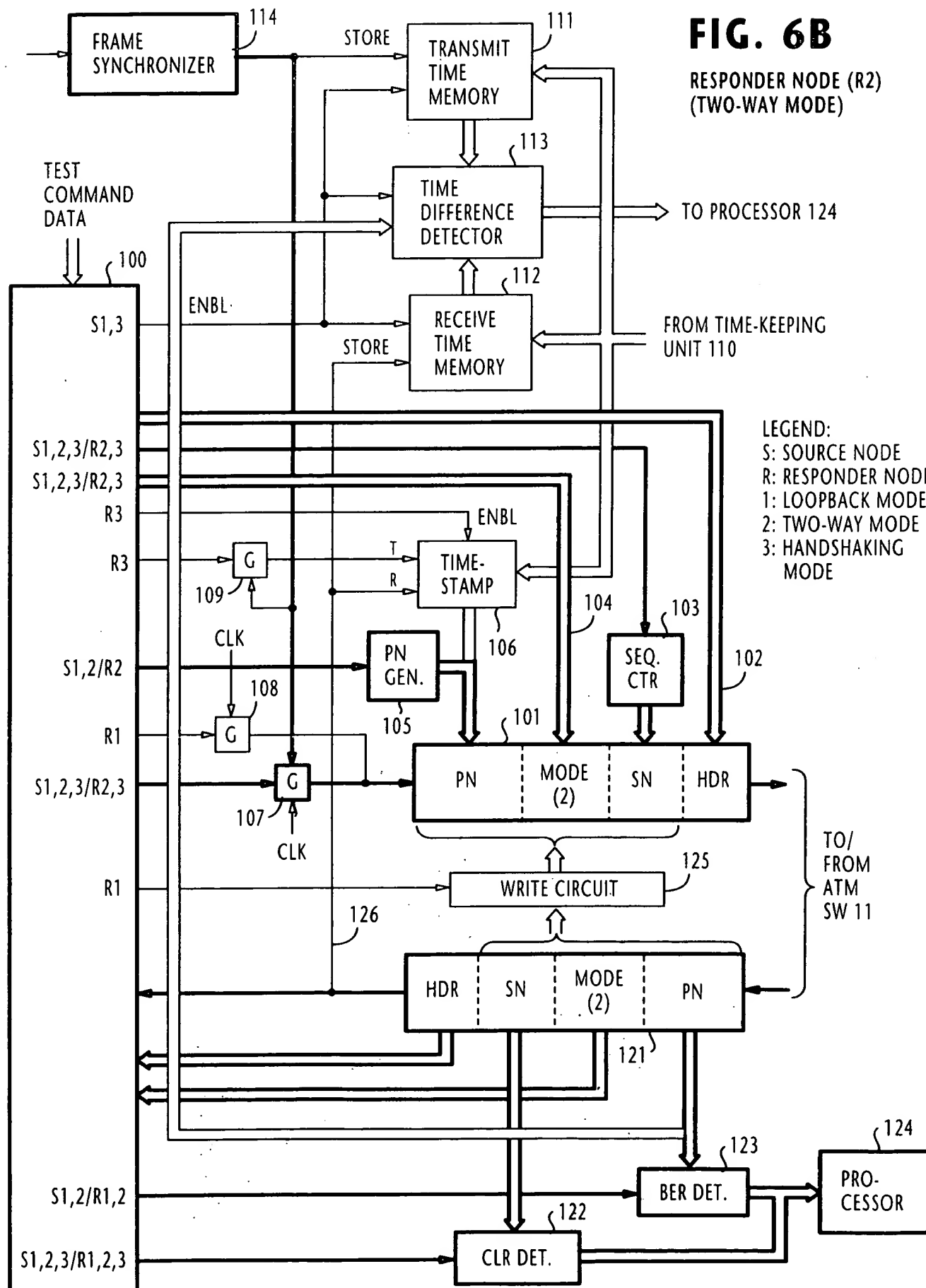
FIG. 6B**RESPONDER NODE (R2)
(TWO-WAY MODE)**

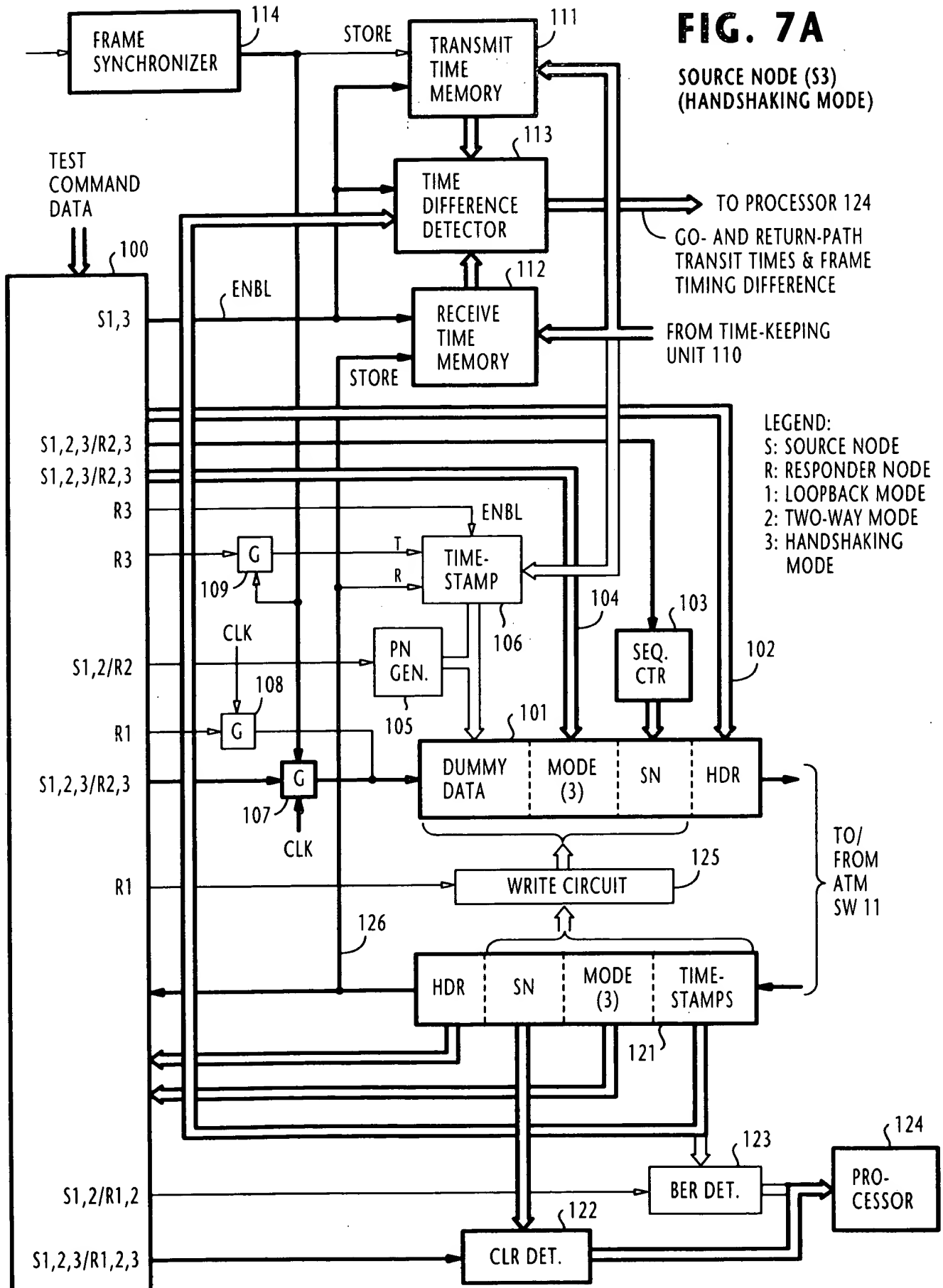
FIG. 7A**SOURCE NODE (S3)
(HANDSHAKING MODE)**

FIG. 7B
RESPONDER NODE (R3)
(HANDSHAKING MODE)

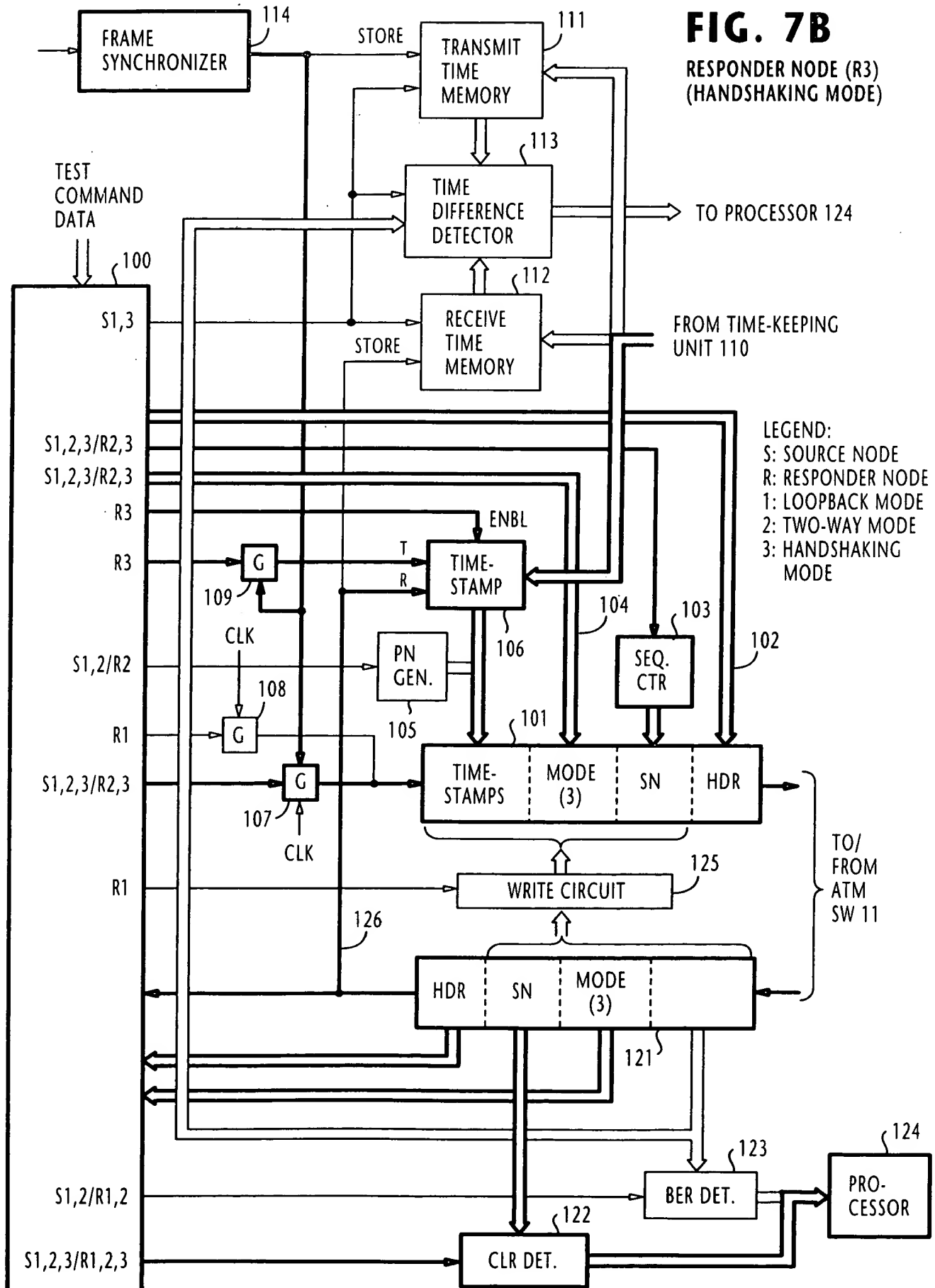


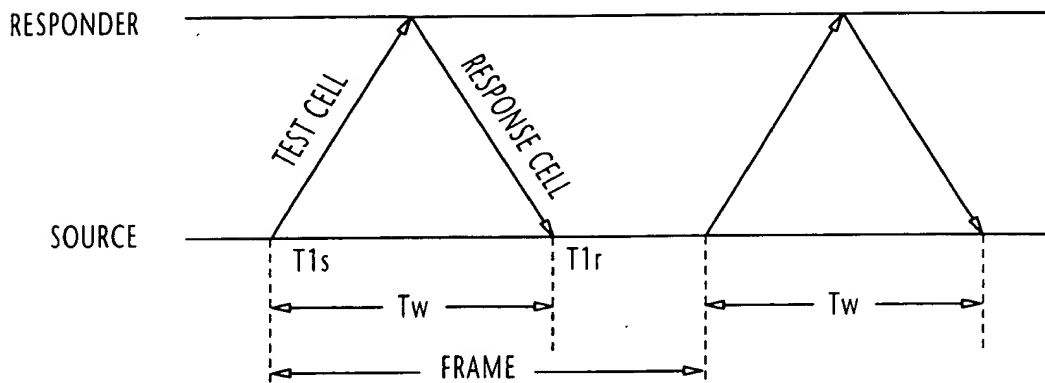
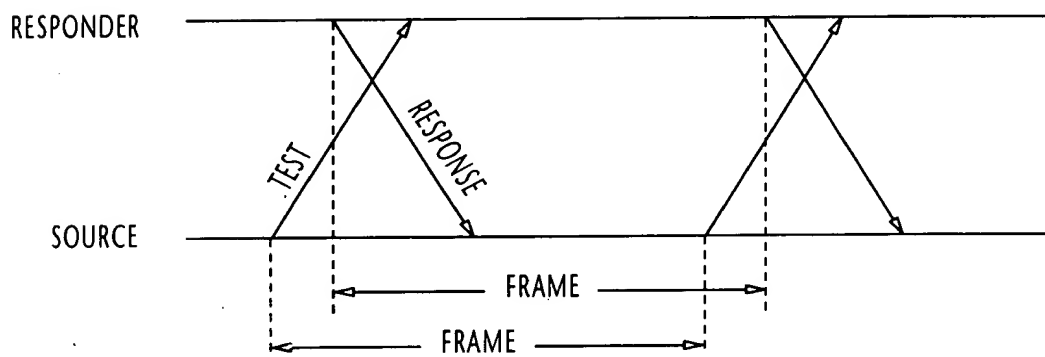
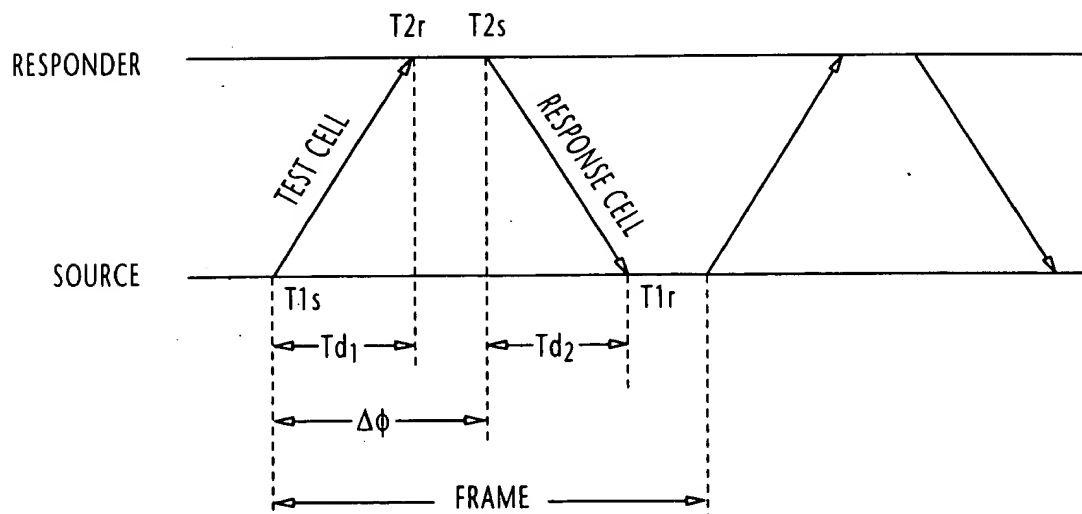
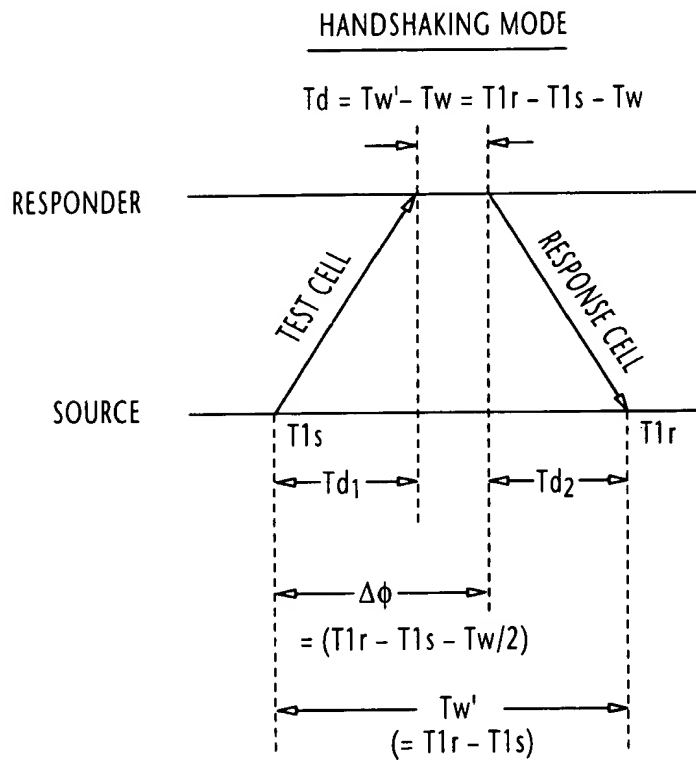
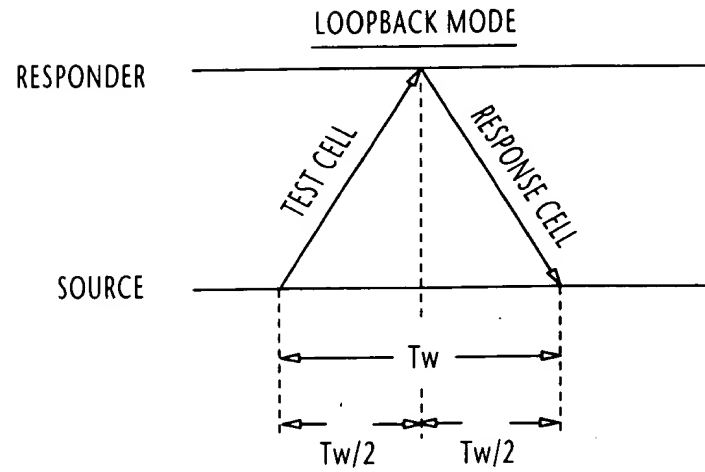
FIG. 8A LOOPBACK MODE**FIG. 8B** TWO-WAY MODE**FIG. 8C** HANDSHAKING MODE

FIG. 9

$$T_{d1} = \Delta\phi - T_d = \Delta\phi - (T_{1r} - T_{1s} - T_w)$$

$$T_{d2} = T_w' - \Delta\phi = T_{1r} - T_{1s} - \Delta\phi$$

FIG. 10